

Galilean satellite ephemerides E5

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Abstract. New ephemerides of Jupiter's Galilean satellites are produced from an analysis of CCD astrometric data, Voyager-mission optical navigation images, mutual event observations, photographic plates, and eclipse timing observations. The resulting parameters, for use in the galsat computer software, are in the B1950 frame for use by the Galileo space mission. Results in the J2000 system are also available.

Key words: astrometry — celestial mechanics — ephemerides — Planets and satellites: Jupiter

1. Introduction

This paper documents the Galilean satellite ephemerides designated as E5, which were delivered in support of the Galileo space mission to Jupiter. The E5 ephemerides supersede the E4 ephemerides, which were developed (Lieske 1994a) without using CCD astrometric data in order to assess the new data type. It is believed that the E5 ephemerides are better than the E3 and E4 ephemerides and they are recommended for general usage. The parameters of E5 are given in the B1950 system so that the galsat software (Lieske 1977) can be employed directly to compute coordinates in the B1950 frame, which has been adopted for the Galileo mission.

The ephemerides E2 (Lieske 1980) were developed prior to the Voyager mission and were based solely on an analysis of earth-based observations. The E2 ephemerides utilized mutual event data from 1973 (Aksnes & Franklin 1976), photographic astrometric observations from 1967-1978 (Pascu 1977 1979), and Jovian satellite eclipse timings from 1878-1974 (Pickering 1907; Pierce 1974; Lieske 1980).

Post-Voyager mission ephemeris improvements yielded ephemerides E3, which included Voyager optical navigation astrometric data and Voyager-derived physical constants (Campbell & Synnott 1985). The E3 ephemerides

employed mutual event data from 1973 and 1979 (Aksnes et al. 1984), Voyager optical navigation astrometric measurements from 1979 (Synnott et al. 1982), additional photographic observations by D. Pascu from 1973-1979, and eclipse timings from 1652 to 1983 (Lieske 1986, 1987).

The initial pre-Galileo mission ephemerides were designated E4 (Lieske 1994a) and included extended mutual event data and photographic data, but no CCD observations, since they were still in the process of being evaluated. The E4 ephemerides employed the previously mentioned Voyager data, mutual event data from 1973 and 1979 corrected for phase effects by adding δt to the observation time (Aksnes et al. 1986), photographic data and Jovian eclipse timings, as well as additional mutual event astrometric measurements from 1985 and 1991 (Aksnes et al. 1986; Franklin et al. 1991; Kaas et al. 1997; Descamps 1994; Goguen et al. 1988; Goguen 1994; Mallama 1992), and additional photographic observations from Pascu (1993) covering the interval 1980-1991. Three-years' of CCD data from Flagstaff (Monet et al. 1994; Owen 1995) were evaluated, but not employed in developing the E4 ephemerides.

The E5 ephemerides represent the most current evolution of the Galilean satellite ephemerides and incorporate all of the above data types, including an evaluation the Doppler data of Ostro et al. (1992).

The 50 parameters which define the theory of motion of the Galilean satellites (Lieske 1977) could also be transformed in a manner such that the same galsat computer program can be employed to compute rectangular coordinates with their values being in the J2000 system. Documentation and an algorithm for such transformation of all galsat-related ephemerides (e.g., Lieske 1977, 1980; Arlot 1982; Vasundhara 1994) will be issued later. In the meantime the equatorial coordinates can be transformed in the following manner.

For the Galileo mission, all input quantities are in the B1950 frame and Earth equatorial coordinates

transformation from B1950 to J2000 when necessary is done by the matrix multiplication

$$r_{\text{J2000}} = Ar_{\text{B1950}}, \quad (1)$$

where the matrix A could be taken from that recommended by IAU Commission 20 (West 1992),

$$A = P_{\text{IAU}} R_3(-0''.525) \quad (2)$$

with P_{IAU} being the standard IAU precession matrix from B1950 to J2000 (Lieske 1979),

$$P_{\text{IAU}} = R_3(-z_A) R_2(\theta_A) R_3(-\zeta_A) \quad (3)$$

or A could be taken from the earlier discussion of Standish (1982), which was developed for transforming from DE118 to DE200,

$$A = R_3(+0''.00073) P_{\text{IAU}} R_3(-0''.53160). \quad (4)$$

It essentially consists of a rotation ΔE in the B1950 equatorial plane from the FK4 origin to the dynamical equinox and then precessing from B1950 to J2000 using the IAU 1976 equatorial precession parameters P_{IAU} (Lieske et al. 1977).

The matrix A could also be derived from Lieske's discussion (1994b) on the precession of orbital elements,

$$A = R_1(-\varepsilon_{\text{J2000}}) R_3(L') R_1(-J_A) R_3(-L) R_1(\varepsilon_{\text{B1950}}). \quad (5)$$

For the Galileo mission, the method of Standish given in Eq. (4) is employed to precess from B1950 to J2000.

The rotation matrices R_i are the standard matrices for rotations about the x , y , or z axes for $i = 1, 2, 3$:

$$\begin{aligned} R_1 &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & \sin \theta \\ 0 & -\sin \theta & \cos \theta \end{bmatrix} \\ R_2 &= \begin{bmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{bmatrix} \\ R_3 &= \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}. \end{aligned} \quad (6)$$

The various matrices mentioned in Eqs. (2), (4) and (5) are presented in Table 1. The maximum difference in satellite coordinates, due to the different precessional transformations, is about 1.5 km, so any of the previously mentioned matrices could be used in a practical situation.

2. The basic parameters

In the galsat-type ephemerides, the Jovicentric Earth-equatorial coordinates of the Galilean satellites are computed as a function of 50 "galsat" parameters (Lieske

1977). The definitions of the basic parameters upon which the theory depends are given in Tables 2 and 3. It is seen that they are a combination of physical parameters and orbital elements.

In the E5 ephemerides, we employed the satellite masses ($\varepsilon_1 - \varepsilon_4$) and Jupiter pole which were determined by Campbell & Synnott (1985) from their analysis of the Voyager data. The Jupiter pole is a function of the longitude of the origin of the coordinates ψ [theory parameter β_{15}], and the inclination I_J of Jupiter's equator to Jupiter's orbit [theory parameter ε_{25}], with some dependence upon the Jupiter orbital inclination to the ecliptic [theory parameter ε_{26}], Jupiter's node Ω_J [theory parameter β_{22}], and the obliquity ε of the ecliptic [theory parameter ε_{27}]. The mass of the Jupiter system was that of JPL ephemeris DE140 (Standish & Folkner 1995) *Sun/Jupiter-system* = 1047.3486. Ephemerides E3 and E4 employed Jupiter system masses which are consistent with JPL ephemeris DE125 (Standish 1985), *Sun/Jupiter-system* = 1047.349. The Jupiter pole employed was $\alpha_J = 268^\circ.001$ and $\delta_J = 64^\circ.504$ at the theory epoch JED 2443000.5 and in the B1950 frame. The rate of ψ [theory parameter β_{15}] models the secular motion of Jupiter's pole from the theory epoch. Jupiter's oblateness parameters J_2 and J_4 were also taken from the Campbell & Synnott analysis. They correspond to theory parameters ε_{11} and ε_{12} in Table 2.

Over the years different tables of ΔT have been used for the calculation of Ephemeris Time (barycentric dynamical time TDB) minus Universal Time. The appropriate table of ΔT values depends upon what model of the Moon's tidal acceleration one adopts. The Earth's Moon was most often used to determine values of ΔT prior to 1955 because of its rapid motion. The derived values of ΔT effectively depend upon a partitioning into portions due to lunar tidal effects versus real changes in ΔT . It essentially depends upon the parameter employed to describe the lunar tidal acceleration \dot{n}_{Moon} . The classical determination of $\dot{n}_{\text{Moon}} = -22.44$ arcsec/cy² by Spencer Jones (1939) was employed for the E1 and E2 (Lieske 1980) ephemerides by means of the Brouwer (1952) and Martin (1969) values of ΔT , which were on the Spencer Jones system.

The Morrison and Ward (1975) value of $\dot{n}_{\text{Moon}} = -26.0$ arcsec/cy² was used for E3, E4 and E5. Tables of ΔT given by Stephenson & Morrison (1984) can be adjusted for any \dot{n}_{Moon} by the technique noted in Lieske (1987) for times prior to 1955.5 by computing

$$\Delta T(\dot{n}_{\text{Moon}}) = \Delta T_{\text{Morrison}} - 0.911(\dot{n}_{\text{Moon}} + 26)T_0^2 \text{ sec} \quad (7)$$

where T_0 is measured in centuries from the 1955.5 epoch of Morrison (1980). The theory parameters of E1 and E2 are consistent with the Spencer-Jones value of \dot{n}_{Moon} , while those for E3 through E5 are consistent with that of Morrison and Ward.

Table 1. Matrices for precession from B1950 to J2000

Eq. (2): Commission 20 matrix from $P_{1\text{AU}}R_3(-0''.525)$

0.9999256794956877	-0.0111814832204662	-0.0004859003815359
0.0111814832391717	0.9999374848933135	-0.0000271625947142
0.0048590037723143	-0.0000271702937440	0.9999881946023742

Eq. (4): Standish matrix from $R_3(+0''.00073)P_{1\text{AU}}R_3(-0''.53160)$

0.9999256791774783	-0.0111815116768724	-0.0048590038154553
0.0111815116959975	0.9999374845751042	-0.0000271625775175
0.0048590037714450	-0.0000271704492210	0.9999881946023742

Eq. (5): Lieske matrix from $R_1(-\epsilon_{\text{J2000}})R_3(L')R_1(-J_{\text{A}})R_3(-L)R_1(\epsilon_{\text{B1950}})$

0.9999256795268940	-0.0111810778339439	-0.0004859930159015
0.0111810775053504	0.9999374894281627	-0.0000272382503387
0.0048599309149990	-0.0000271030297995	0.9999881900987267

Table 2. Definition of theory parameters ϵ

Epsilon Parameter		Generating value	Description
1	m_1	$449.7 \cdot 10^{-7}(1 + \epsilon_1)$	Mass of Satellite I relative to Jupiter
2	m_2	$252.9 \cdot 10^{-7}(1 + \epsilon_2)$	Mass of Satellite II relative to Jupiter
3	m_3	$798.8 \cdot 10^{-7}(1 + \epsilon_3)$	Mass of Satellite III relative to Jupiter
4	m_4	$450.4 \cdot 10^{-7}(1 + \epsilon_4)$	Mass of Satellite IV relative to Jupiter
5	S/J	$1047.355(1 + \epsilon_5)$	Mass of Sun relative to Jupiter
6	n_1	$203.48895 \cdot 4208(1 + \epsilon_6)$	Mean motion of Satellite I, deg/day
7	n_2	$101.37472 \cdot 3445(1 + \epsilon_7)$	Mean motion of Satellite II, deg/day
8	n_4	$21.57107 \cdot 1403(1 + \epsilon_8)$	Mean motion of Satellite IV, deg/day
9	λ_{A}	$180^\circ \epsilon_9 / \pi$	Amplitude of free libration, λ_{A} in deg, ϵ_9 in rad
10	n_{J}	$8.30912 \cdot 15712 \cdot 10^{-2}(1 + \epsilon_{10})$	Mean motion of Jupiter, deg/day
11	J_2	$0.01484 \cdot 85(1 + \epsilon_{11})$	Jupiter J_2
12	J_4	$-8.107 \cdot 10^{-4}(1 + \epsilon_{12})$	Jupiter J_4
13	R_{J}	$71420(1 + \epsilon_{13})$	Radius of Jupiter, km
14	P_{J}	$9.92482 \cdot 5(1 + \epsilon_{14})$	Period of Jupiter rotation, hr
15	$3(C - A)/2C$	$0.111(1 + \epsilon_{15})$	Ratio of Jupiter moments of inertia
16	e_{11}	$465 \cdot 10^{-7}(1 + \epsilon_{16})$	Primary eccentricity of Satellite I, rad
17	e_{22}	$825 \cdot 10^{-7}(1 + \epsilon_{17})$	Primary eccentricity of Satellite II, rad
18	e_{33}	$15164 \cdot 10^{-7}(1 + \epsilon_{18})$	Primary eccentricity of Satellite III, rad
19	e_{44}	$73725 \cdot 10^{-7}(1 + \epsilon_{19})$	Primary eccentricity of Satellite IV, rad
20	e_{J}	$0.04846 \cdot 02472(1 + \epsilon_{20})$	Eccentricity of Jupiter
21	c_{11}	$4756 \cdot 10^{-7}(1 + \epsilon_{21})$	Primary sine inclination of Satellite I
22	c_{22}	$81490 \cdot 10^{-7}(1 + \epsilon_{22})$	Primary sine inclination of Satellite II
23	c_{33}	$31108 \cdot 10^{-7}(1 + \epsilon_{23})$	Primary sine inclination of Satellite III
24	c_{44}	$47460 \cdot 10^{-7}(1 + \epsilon_{24})$	Primary sine inclination of Satellite IV
25	I_{J}	$3.10401(1 + \epsilon_{25})$	Inclination of Jupiter orbit to Jupiter equator, deg
26	J	$1.30691(1 + \epsilon_{26})$	Inclination of Jupiter orbit to ecliptic, deg
27	ϵ	$23^\circ 26' 44''.84(1 + \epsilon_{27})$	Inclination (Obliquity) of ecliptic to Earth equator deg
28	n_{S}	$3.34597 \cdot 33896 \cdot 10^{-2}(1 + \epsilon_{28})$	Mean motion of Saturn, deg/day

Table 3. Definition of theory parameters β

Beta Parameter		Epoch value (deg)	Description
1	ℓ_1	$106^{\circ}03042 + \beta_1$	Mean longitude of Satellite I
2	ℓ_2	$175^{\circ}74748 + \beta_2$	Mean longitude of Satellite II
3	ℓ_3	$[120^{\circ}60601 - \frac{1}{2}\beta_1 + \frac{3}{2}\beta_2]$	Mean longitude of Satellite III
4	ℓ_4	$84^{\circ}51861 + \beta_4$	Mean longitude of Satellite IV
5	ϕ_λ	β_5	Free Libration $\psi_1 - 3\psi_2 + 2\psi_3 = \pi + \epsilon_9 \sin \phi_\lambda$ $= 180^{\circ} + \lambda_A \sin \phi_\lambda$
6	π_1	$4^{\circ}51172 + \beta_6$	Proper periapse of Satellite I
7	π_2	$74^{\circ}53051 + \beta_7$	Proper periapse of Satellite II
8	π_3	$174^{\circ}85831 + \beta_8$	Proper periapse of Satellite III
9	π_4	$336^{\circ}02667 + \beta_9$	Proper periapse of Satellite IV
10	Π_J	$13^{\circ}30364 + \beta_{10}$	Longitude of perihelion of Jupiter
11	ω_1	$242^{\circ}73706 + \beta_{11}$	Proper node of Satellite I
12	ω_2	$95^{\circ}28556 + \beta_{12}$	Proper node of Satellite II
13	ω_3	$125^{\circ}14673 + \beta_{13}$	Proper node of Satellite III
14	ω_4	$317^{\circ}89250 + \beta_{14}$	Proper node of Satellite IV
15	ψ	$316^{\circ}73369 + \beta_{15}$	Longitude of origin of coordinates (Jupiter's pole)
16	G'	$31^{\circ}97852\ 80244 + \beta_{16}$	Mean anomaly of Saturn
17	G	$30^{\circ}37841\ 20168 + \beta_{17} + \delta G$	Mean anomaly of Jupiter
18	ϕ_1	$172^{\circ}84(1 - 0.014\epsilon_{20}) + \beta_{18}$	Phase angle in solar $(A/R)^3$ with angle $2G' - G$
19	ϕ_2	$47^{\circ}03(1 - 0.156\epsilon_{20}) + \beta_{19}$	Phase angle in solar $(A/R)^3$ with angle $5G' - 2G$
20	ϕ_3	$259^{\circ}18 + \beta_{20}$	Phase angle in solar $(A/R)^3$ with angle $G' - G$
21	ϕ_4	$157^{\circ}12(1 + 0.0014\epsilon_{20}) + \beta_{21}$	Phase angle in solar $(A/R)^3$ with angle $2G' - 2G$
22	Ω_J	$99^{\circ}95326 + \beta_{22}$	Longitude ascending node of Jupiter's orbit on ecliptic

Beta Symbol		Rate (deg/day)	Description
1	$\dot{\ell}_1$	$203^{\circ}48895\ 4208(1 + \epsilon_6)$	Mean motion of Satellite I
2	$\dot{\ell}_2$	$101^{\circ}37472\ 3445(1 + \epsilon_7)$	Mean motion of Satellite II
3	$\dot{\ell}_3$	$[50^{\circ}31760\ 80635\{1 - 2\epsilon_6 + 3\epsilon_7 - 0.02204\ 51849\ 7(\epsilon_6 - \epsilon_7)\}]$	Mean motion of Satellite III
4	$\dot{\ell}_4$	$21^{\circ}57107\ 1403(1 + \epsilon_8)$	Mean motion of Satellite IV
5	$\dot{\phi}_\lambda$	$\sqrt{L} (= 0^{\circ}1737\ 9190 + \dots)$	Rate of free libration (Fiche Table A.30)
6	$\dot{\pi}_1$	$(0^{\circ}1613\ 8586 + \dots)$	Proper periapse rate of Satellite I
7	$\dot{\pi}_2$	$(0^{\circ}0472\ 6307 + \dots)$	Proper periapse rate of Satellite II
8	$\dot{\pi}_3$	$(0^{\circ}0071\ 2734 + \dots)$	Proper periapse rate of Satellite III
9	$\dot{\pi}_4$	$(0^{\circ}0018\ 4000 + \dots)$	Proper periapse rate of Satellite IV
10	$\dot{\Pi}_J$	0	
11	$\dot{\omega}_1$	$(-0^{\circ}1327\ 9386 + \dots)$	Proper node rate of Satellite I
12	$\dot{\omega}_2$	$(-0^{\circ}0326\ 3064 + \dots)$	Proper node rate of Satellite II
13	$\dot{\omega}_3$	$(-0^{\circ}0071\ 7703 + \dots)$	Proper node rate of Satellite III
14	$\dot{\omega}_4$	$(-0^{\circ}0017\ 5934 + \dots)$	Proper node rate of Satellite IV
15	$\dot{\psi}$	$(-0^{\circ}0000\ 0208 + \dots)$	Longitude of origin rate
16	\dot{G}'	$3^{\circ}34597\ 33896 \cdot 10^{-2}(1 + \epsilon_{28})$	Mean motion of Saturn
17	\dot{G}	$8^{\circ}30912\ 15712 \cdot 10^{-2}(1 + \epsilon_{10})$	Mean motion of Jupiter
18...22		0	

3. The observations

A variety of different observational data types were employed in developing ephemerides E5. A new and very powerful data type of CCD observations from the U.S. Naval Observatory Flagstaff Station was used for the first time, together with very accurate Voyager optical navigation data from 1979 and the mutual event observations 1973-1991, photographic observations of D. Pascu from 1967-1993 and Jovian eclipse timings from 1652-1983. Doppler observations from 1987-1991 were employed to assess the value of the Doppler data and evaluate the ephemerides.

Table 4. Observational data employed for ephemeris E5

Data span	observable type	observ.	% chg
1992-1994	CCD data, Flagstaff ra & dec	870	-52.6
1979	Voyager opnav ra & dec	366	-19.0
1973-1991	mutual events ra & dec	860	-55.5
1967-1993	photographic ra & dec	8462	-3.2
1652-1983	eclipse timings	15711	+2.7
1994	CCD data, Table Mountain	72	+68.3
1987-1991	Doppler	50	-55.6

By intercomparing various data types one learns of the strengths and weaknesses of each individual type of data and discovers inconsistencies among the data types. The data are described in Table 4, which also gives the percentage change in weighted sum-of-squares for ephemeris E5 relative to ephemeris E3. A plus sign indicates an increase and a minus sign indicates a decrease in the weighted residuals. The various data types were combined by weighting each observation by the reciprocal of its squared a priori standard deviation. A common data set (including weights) was employed to evaluate all ephemerides so that one can compare the relative merits of a given ephemeris to a common data set. Thus, although no CCD observations were employed in the development of ephemeris E3, the residuals of the CCD data employed in this paper are also given for ephemeris E3 so that the reader can make meaningful comparisons.

In order to more closely compare the various ephemerides with the different data types, we present in Table 5 the residuals of unit weight for each data type for the different ephemerides E2 through E5 by Lieske, as well as for the Bureau des Longitudes' ephemeris G5 (Arlot 1982). In comparing Table 4 with Table 5 it should be remembered that Table 4 is related to the square of the residuals while Table 5 employs the square root of the sum-of-squares. The comparison for Flagstaff CCD data, for example, for Table 5 would indicate that the Table 4 entry should be about $(29/43)^2 - 1 = -54.5\%$ for the E5 vs E3 comparison.

Table 5. Observational rms residuals for various ephemerides

Observable type	E2	G5	E3	E4	E5
CCD Flagstaff, mas	43	40	43	32	29
Voyager opnav, mas	1309	1334	929	904	820
mutual events, mas	62	53	62	47	46
photographic, mas	107	106	106	104	104
eclipse timings, sec	55.5	74.5	53.2	53.9	53.9
CCD Table Mtn, mas	43	73	41	52	53
Doppler, Hz	15.3	18.4	13.7	11.7	11.9

3.1. CCD observations

The new CCD observations were made at the U.S. Naval Observatory Flagstaff Station (A. Monet et al. 1994) during the years 1993-1995, employing techniques developed by D. Monet and described in Monet et al. (1992) and in Monet & Monet (1992). The Flagstaff data were processed at JPL by W. Owen who produced normal-point residuals, typically from 30-50 CCD "exposures", for the author using ephemeris E3. Those residuals were then employed by the author to generate pseudo-observable "normal-point observations" by adding the residual to an artificially-constructed computed position at the mean time of the CCD exposures using the same ephemeris which was employed in computing the CCD residuals. Such a "normal point observation" could be employed with other astrometric data in an analysis of the observations, and should represent a valid description of the actual CCD observations. Additionally, the pseudo-observations will serve the purpose of archiving the CCD observations in convenient form. In processing the CCD data Owen would estimate the pointing and orientation parameters and employ a single telescope scale factor (modified for refraction and atmospheric effects) for all the Flagstaff data and he would use a single ephemeris (viz. E3) which was not adjusted in the reduction process. If that procedure is valid, then the pseudo-observables generated should behave like valid observational data, viz. the residuals should decrease if one employs a better ephemeris with the original pseudo-observables. It was for this reason that ephemeris E3 was intentionally employed - it was known to need some correction and we desired to explore the validity of the process of constructing normal point pseudo-observables. If the normal points were constructed instead on a different ephemeris, then the pseudo-observables differed by less than 15 km ($0''.005$) from those generated via ephemeris E3, even though the residuals might actually be significantly different using the two ephemerides. That 15-km reproducibility of the normal points is a good indication of the intrinsic accuracy of the CCD data.

Some less-accurate CCD data from the JPL Table Mountain Facility (Owen 1995) were also employed, although with hindsight they probably should not have been

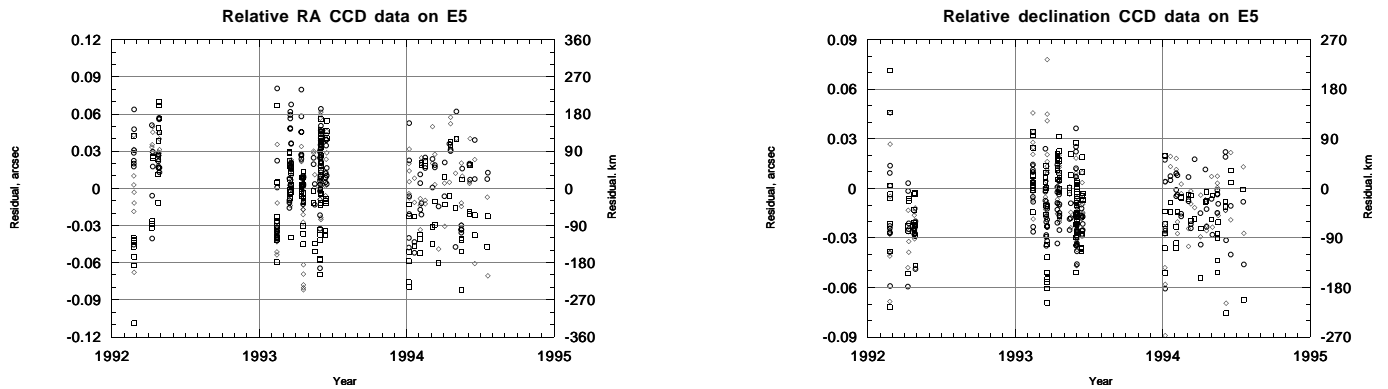


Fig. 1. Residuals in right ascension (left) and declination (right) for Flagstaff CCD observations relative to Satellite 1 using ephemeris E5. The observations of Europa relative to Io are indicated by a \circ , those of Ganymede by a \square , and those of Callisto by a \diamond

included in developing E5. They did not exhibit the reduction of residuals with a better ephemeris, and that is believed to be due to the fact that there were too few Table Mountain data to adequately separate the orbital effects from the telescope effects.

The CCD data were processed using Lambert scattering to compute the offset between the center of light and center of figure (Lindegren 1977) and it is believed that the dominant remaining unmodeled error source in these data is due to albedo variations across the disk of the satellites. Recent estimates of the albedo variations by several scientists (Goguen 1994; Mallama 1993; Riedel 1994; Gaskell 1995) are not entirely consistent and for the Galileo-mission ephemerides it was decided to limit the processing to computation of the difference between center of light and center of figure due to Lambert scattering only, since it represents a reasonable first approximation to the scattering properties of the satellites if one excludes albedo variations (*viz.*, effects which depend upon features on the satellites and which vary with planetocentric longitude of the central disc). The extrapolation of Voyager-derived scattering properties (which occurred at high phase angle) to the scattering properties of the satellites at low phase angle as observed from the Earth is not entirely satisfactory and the several efforts done to date are not entirely consistent with one another. It is hoped that some series of observations made from the Hubble Space Telescope will resolve the problems. Employment of Lambert scattering is a useful first-approximation. The differences between Lambert, Minnaert or Hapke scattering laws is minor compared to the albedo variations introduced by physical features on the satellites, which may introduce center-of-light relative to center-of-figure variations on the order of 75 – 100 km.

The Flagstaff CCD data were weighted using a standard deviation of $0''.03$, which corresponds to about 90 km for these earth-based observations. The Table Mountain

data were weighted using a standard deviation of $0''.05$, corresponding to about 150 km.

3.2. Voyager optical navigation data

During the Voyager mission in 1979, some optical navigation images of the Jovian satellites were taken from the spacecraft for use in navigating the spacecraft to the Jovian encounter. We have 183 observations of the Jovian satellites in right ascension and in declination, made during the Voyager I and Voyager II encounters (Synnott et al. 1982). The optical navigation images are analogous to earth-based astrometric observations of the satellites except that the “opnav” images are taken by an “observer” much closer to the Jovian system (typically 13 – 95 light seconds from the satellites). At $5 \cdot 10^6$ km from Jupiter, one arcsec corresponds approximately to 25 km. Additionally, the spacecraft-based observations are the result of analyzing extended satellite images. By inferring the center of the satellite from observations of the limb, the Voyager data do not have the center-of-light vs center-of-figure problems which are common to disk-integrated images such as those contained in CCD observations and photographic plates and mutual events. The Voyager data were weighted using a standard deviation of $1''.0$ (as seen at the spacecraft’s distance from Jupiter). For spacecraft-to-satellite distances of 13 – 95 light seconds, the $1''.0$ corresponds to 19 and 140 km respectively for these spacecraft-based observations. The Voyager optical navigation residuals on ephemeris E5 are depicted for right ascension and declination in Fig. 2.

3.3. Mutual event astrometric data

Since 1973 there have been successful campaigns to observe the mutual event seasons every six years, when the Jovian satellites eclipse and occult one another as the Sun and the Earth pass through the plane of the Jovian equator, in which the satellite orbits lie. Aksnes and colleagues

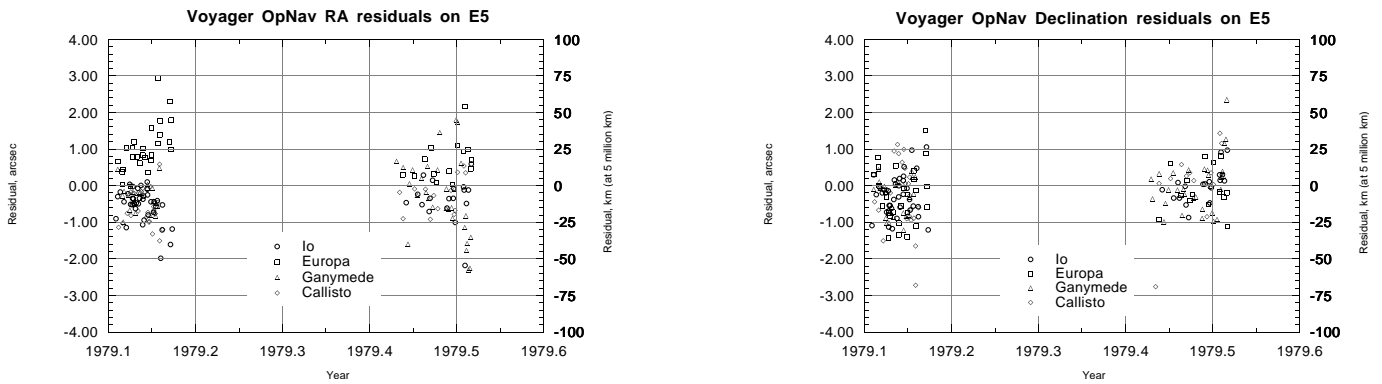


Fig. 2. Residuals in right ascension (left) and declination (right) for the Voyager optical navigation observations using ephemeris E5. The ordinate is in arcsec with an approximate corresponding linear distance scale on the right. Jupiter-relative observations of Io are indicated by \circ , Europa by \square , Ganymede by \triangle , and Callisto by \diamond

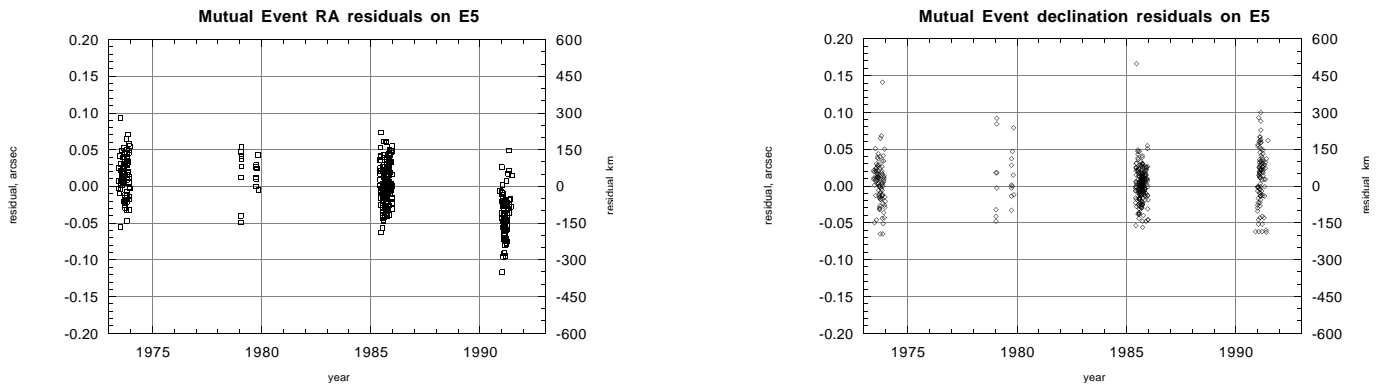


Fig. 3. Residuals in right ascension (left) and declination (right) for astrometric mutual event observations using ephemeris E5. The ordinate is in arcsec with an approximate corresponding linear distance scale on the right

(Aksnes 1974, 1984; Aksnes & Franklin 1978, 1990), along with Arlot and colleagues (Arlot 1978, 1984, 1990, 1996), have made predictions of such mutual events available to scientists throughout the world and have organized scientific programs to observe the mutual events. Aksnes' team has produced astrometric separations of the satellites, at times near the mid-event times, which are very useful for ephemeris development purposes.

The early Galilean satellite ephemerides E1 and E2 (Lieske 1980) employed the Aksnes data from 1973 (Aksnes & Franklin 1976) and 1979 (Aksnes et al. 1984) and were affected by the phase offsets between eclipses and occultations which led Aksnes et al. (1986) to recommend that δt be added to the published observation times for the 1973 and 1979 data. The ephemerides E3 were generated using the recommended additions of δt to the observation times in processing the 1973 and 1979 mutual events astrometric data.

In the processing of mutual event observations by the Aksnes team in 1985 (Franklin et al. 1991) and 1991 (Kaas et al. 1997), it was intended that no value of δt would be required but that instead the authors would incorporate the phase effects into their published times and separa-

tions. However, the effects were added in the incorrect direction for the published data and hence it is recommended (Aksnes 1993; Franklin 1993; Lieske 1995) that the 1985 and 1991 Aksnes data be employed by adding *twice* the published values of the δt phase corrections to the observation times. Essentially the first addition of δt removes the erroneous application of the phase effects with the incorrect sign and the second application of δt actually corrects for the phase problem. Additionally, some infra-red astrometric mutual event separations were obtained from Goguen et al. (1988) in 1985 as well as in 1991 (Goguen 1994). Astrometric separations from the 1991 mutual event season which were employed in the development of E5 were also published by Mallama (1992a), Spencer (1993) and by Descamps (1994).

The mutual event data were weighted using standard deviations of $0''.020$ to $0''.045$, which corresponds to 60 km and 140 km respectively for these earth-based observations. The typical weight corresponds to a standard deviation of $0''.030$ or 90 km.

The obvious offset in right ascension residuals for the 1991 mutual event season depicted in Fig. 3 is believed not to be due to ephemeris errors, but rather is due to albedo

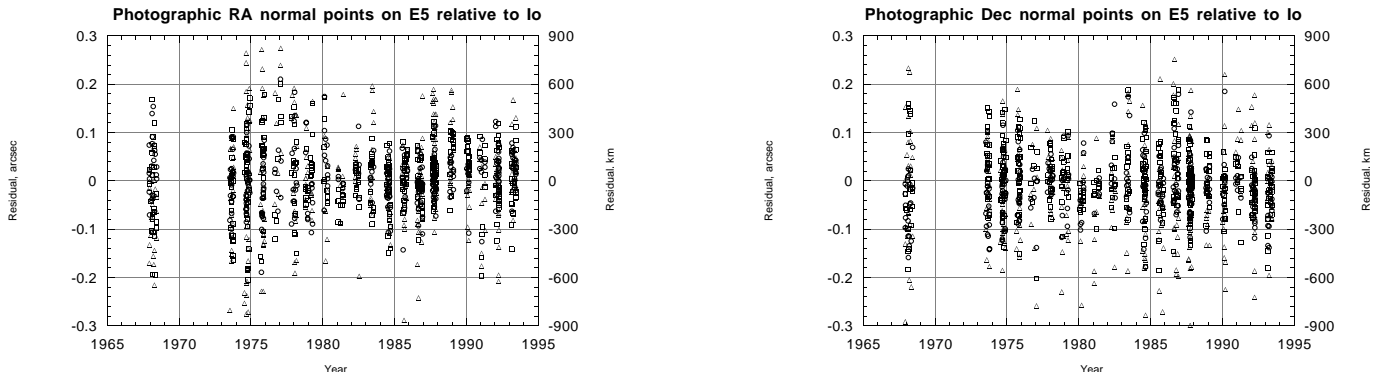


Fig. 4. Residuals in right ascension (left) and declination (right) for photographic observations relative to Io using ephemeris E5. The residuals for exposures of a given satellite on each plate have been combined to produce a normal point for each plate. Observations of Europa relative to Io are indicated by a \circ , those of Ganymede by a \square and those of Callisto by a \diamond

effects since almost all of the 1991 mutual event observations involved Io and were made at comparable longitudes on the satellite disk. The CCD and photographic data, for example, show no such offset and those data were sampled at various longitudes.

3.4. Photographic observations

The long and valuable series of photographic observations made by D. Pascu of the U.S. Naval Observatory have been an essential ingredient of the Galilean satellite ephemerides since the first development of the Galsat software. In an extended series of observations 1967–1993, Pascu (1977, 1979, 1993, 1994) provided astrometric observations of the satellites. He pioneered the development of neutral density filters to enable the accurate observation of the Galilean satellites on a regular basis. The Pascu data were reduced using a single scale factor (modified by adjustments for refraction for each observation) for the ensemble of observations, as determined by Pascu. Additionally, a correction to the Pascu scale was applied for a refraction-related effect, amounting to a relative change in scale of $-58''/206265$, which probably resulted from the manner in which the plate scale was originally determined.

The photographic data from 1967 through 1975 were weighted using a standard deviation of $0''.13$ per exposure, while those from 1976 onwards were weighted using a standard deviation of $0''.09$ per exposure, corresponding to position uncertainties of 400 km and 275 km, respectively, for each exposure. A photographic plate typically consisted of 4 exposures of each satellite.

The residuals on E5 for photographic observations are plotted in Fig. 4. In the figure, normal-point residuals are presented for each photographic plate, in order to make the comparison with the normal-point CCD observations more feasible. In the plots, the residuals for all exposures of a given satellite on a single plate are averaged into a single normal-point residual.

3.5. Jupiter eclipse timings

The Jovian eclipse timings, representing the classical observations of the Galilean satellites back to the 17th century, were discussed in Lieske (1986a,b). The early data are from the Pingré 17th century collection later published by Bigourdan (1901), and from the Delisle collection (Bigourdan 1897). The book on 17th century astronomy by Pingré published by Bigourdan was originally scheduled for publication 100 years earlier by Pingré. But Pingré’s death and the French revolution intervened, and the printer’s proof copies were destroyed as scrap paper. It was only 100 years later that a copy of the proofs was found and ultimately published by the Paris Academy. The manuscript collection of J.-N. Delisle contains a wealth of historically and scientifically interesting observations of Galilean satellite eclipses. These two collections effectively re-construct the “lost” Delambre collection.

We employed satellite radii of 1815, 1569, 2631 and 2400 km for Io through Callisto, respectively (Davies et al. 1985), in reducing the eclipse timings.

Additionally, the series of eclipse observations by Pickering from 1878–1903 (Pickering 1907) and those accumulated by Pierce (1974), together with those of many amateur astronomers, especially those coordinated by B. Loader and J. Westfall, were employed. Finally, a few eclipse timings by Mallama (1992b) taken in 1990–91 were analyzed.

The eclipse timing data were employed with average standard deviations between 44 s for Io and 150 s for Callisto with a mean of 63 s, which correspond to position uncertainties of 775 km for Io, 1225 km for Callisto, and 800 km on the average for all satellites. The residuals appear visually similar to those depicted in Lieske (1986a) and therefore they are not presented here again.

Table 6. Values of theory parameters ε and β for E5 in B1950 frame [see also Tables 2 and 3]

Parameter	Related to	Value	Parameter	Related to	Value
ε_1	m_1	0.046323 (± 0.000813)	ε_{26}	J	-0.000137 (± 0.000117)
ε_2	m_2	-0.000906 (± 0.001394)	ε_{27}	ϵ	0.000000 (± 0.000004)
ε_3	m_3	-0.022997 (± 0.000276)	ε_{28}	n_S	0.000000 (± 0.000001)
ε_4	m_4	0.258508 (± 0.000537)	β_1	ℓ_1	$0^\circ 046767$ (± 0.00218)
ε_5	S/J	$2009.3457E - 07$ ($\pm 8.12E - 07$)	β_2	ℓ_2	$-0^\circ 015865$ (± 0.000835)
ε_6	n_1	$7.7760E - 09$ ($\pm 0.549E - 09$)	β_3	ℓ_3	$[= -\frac{1}{2}\beta_1 + \frac{3}{2}\beta_2]$
ε_7	n_2	$12.7230E - 09$ ($\pm 1.04E - 09$)	β_4	ℓ_4	$-0^\circ 074023$ (± 0.001950)
ε_8	n_4	$-10.4916E - 09$ ($\pm 4.90E - 09$)	β_5	ϕ_λ	$199^\circ 676608$ (± 1.57)
ε_9	λ_A	$11.2104E - 04$ ($\pm 0.391E - 04$) rad	β_6	π_1	$92^\circ 576366$ (± 19.9)
ε_{10}	n_J	$1.63E - 05$ ($\pm 0.13E - 05$)	β_7	π_2	$80^\circ 335825$ (± 1.35)
ε_{11}	J_2	-0.007576 (± 0.000066)	β_8	π_3	$13^\circ 325727$ (± 0.150)
ε_{12}	J_4	-0.275934 (± 0.00631)	β_9	π_4	$-0^\circ 739863$ (± 0.0152)
ε_{13}	R_J	-0.000308 (± 0.000057)	β_{10}	Π_J	$0^\circ 166302$ (± 0.00344)
ε_{14}	P_J	$9.5E - 06$ ($\pm 102.E - 06$)	β_{11}	ω_1	$69^\circ 597506$ (± 0.788000)
ε_{15}	$3(C - A)/2C$	-0.170000 (± 0.0676)	β_{12}	ω_2	$5^\circ 155556$ (± 0.0495)
ε_{16}	e_{11}	-0.995346 (± 0.0291)	β_{13}	ω_3	$-5^\circ 952489$ (± 0.101)
ε_{17}	e_{22}	0.748031 (± 0.0221)	β_{14}	ω_4	$4^\circ 726133$ (± 0.0772)
ε_{18}	e_{33}	-0.051182 (± 0.00167)	β_{15}	ψ	$-0^\circ 215487$ (± 0.00545)
ε_{19}	e_{44}	-0.002434 (± 0.000324)	β_{16}	G'	$0^\circ 000000$ (± 0.407)
ε_{20}	e_J	0.002750 (± 0.000081)	β_{17}	G	$-0^\circ 140855$ (± 0.00279)
ε_{21}	c_{11}	0.344275 (± 0.0196)	β_{18}	ϕ_1	$15^\circ 541000$ (± 0.411)
ε_{22}	c_{22}	-0.005970 (± 0.000872)	β_{19}	ϕ_2	$5^\circ 215000$ (± 0.469)
ε_{23}	c_{33}	0.041611 (± 0.00199)	β_{20}	ϕ_3	$-1^\circ 996000$ (± 0.757)
ε_{24}	c_{44}	-0.070074 (± 0.000810)	β_{21}	ϕ_4	$-7^\circ 968000$ (± 0.293)
ε_{25}	I_J	0.005110 (± 0.000079)	β_{22}	Ω_J	$0^\circ 045266$ (± 0.00664)

3.6. Doppler data

The Doppler observations discussed by Ostro et al. (1992) were employed to evaluate the ephemerides and explore the potential of Doppler data, but they were not included in analysis and the development of E5. The data are consistent with the observations which were analyzed, but they were not included in the analysis because of possible uncertainty in the radar scattering properties of the satellites similar to albedo effects which depend upon the planetocentric longitude. The 50 Doppler observations of the outer three Galilean satellites were made between 1987 and 1991.

The Doppler data were weighted using standard deviations of 19 Hz for Europa, 12 Hz for Ganymede and 10 Hz for Callisto for the Arecibo 13-cm S-band system data.

4. Discussion

The theory parameters which result from the analysis of these data are listed in Table 6, which will produce coordinates in the B1950 frame when used with the galsat software. A future paper will document how they, and any

other set of galsat parameters, can be transformed to the J2000 system in a manner such that the galsat software will directly produce J2000 coordinates. In Table 6, the uncertainties listed for the ε and β parameters are the formal errors obtained in the estimation process. By comparing the coordinates of ephemerides E3 with those of E5 and interpreting those differences to represent a 1- σ error, we obtain a scale factor which should be applied for the formal uncertainties listed in the table. That scale factor ranges between 2.5 and 3, so we recommend that the formal errors be multiplied by 3. The derived values of the angular variables for E5 are given in Table 7. The series coefficients for satellite coordinates ξ , v and ζ are summarized in Table 8 for the E5 ephemerides.

Representing the Jupiter-equatorial projection of the orbital radius by ρ , and the true and mean longitudes by ν and ℓ , respectively, then the equatorial radial component $\xi = (\rho - a)/a$ consists of cosine terms $\xi(t) = \Sigma K_1 \cos \Theta_1(t)$, while the longitude component $v = \nu - \ell$ consists of sine terms $v(t) = \Sigma K_2 \sin \Theta_2(t)$, and the latitude component $\zeta = \bar{z}/a$ consists of sine terms $\zeta(\tau) =$

Table 7. Derived variables for ephemeris E5

Index	Variable	Value (deg)	Rate (deg/day)
1	ℓ_1	106°077187	203°48895579033
2	ℓ_2	175°731615	101°37472473479
3	ℓ_3	120°558829	50°31760920702
4	ℓ_4	84°444587	21°57107117668
5	ϕ_λ	199.676608	0°17379190461
6	π_1	97°088086	0°16138586144
7	π_2	154°866335	0°04726306609
8	π_3	188°184037	0°00712733949
9	π_4	335°286807	0°00183999637
10	Π_J	13°469942	0.
11	ω_1	312°334566	-0°13279385940
12	ω_2	100°441116	-0°03263063731
13	ω_3	119°194241	-0°00717703155
14	ω_4	322°618633	-0°00175933880
15	ψ	316°518203	-2°08362 · 10 ⁻⁶
16	G'	31°978528	0°03345973390
17	G	30°237557	0°08309257010
18	ϕ_1	188°374346	0.
19	ϕ_2	52°224824	0.
20	ϕ_3	257°184000	0.
21	ϕ_4	149°152605	0.
22	Ω_J	99°998526	0.
	a_1		2.819353 · 10 ⁻³ a.u.
	a_2		4.485883 · 10 ⁻³ a.u.
	a_3		7.155366 · 10 ⁻³ a.u.
	a_4		12.585464 · 10 ⁻³ a.u.

$\Sigma K_3 \sin \Theta_3(\tau)$. As developed by Sampson (1921, pp. 229–230), the “time-completed” τ may be defined as

$$\tau = t + v/n, \quad (8)$$

where t is “ephemeris time” (TDB). One can employ the time-completed to compute the latitude quantity $s(t) = \bar{z}/\rho$ from the shorter series for $\zeta(t) = \bar{z}/a$ via the relationship $s(t) = \zeta(t+v/n)$. It effectively amounts to calculating the latitude perturbations as a function of true longitude rather than as a function of mean longitude.

The Jupiter equatorial coordinates $\bar{\mathbf{r}} = (\bar{x}, \bar{y}, \bar{z})^T$ are computed from the orbital components ξ, v, ζ using the equations

$$\begin{aligned} \bar{x} &= a(1 + \xi) \cos(\ell - \psi + v) \\ \bar{y} &= a(1 + \xi) \sin(\ell - \psi + v) \\ \bar{z} &= a(1 + \xi)s. \end{aligned} \quad (9)$$

The Earth-equatorial coordinates $\mathbf{r} = (x, y, z)^T$ are then computed from the Jupiter-equatorial coordinates via the rotation matrices

$$\mathbf{r} = R_1(-\varepsilon)R_3(-\Omega)R_1(-J)R_3(-\psi + \Omega)R_1(-I)\bar{\mathbf{r}}. \quad (10)$$

It is these Earth-equatorial coordinates \mathbf{r} that are provided by the galsat software.

As described in *Theory*, the Earth-equatorial coordinates are constructed from the series for ξ, v and ζ by the relationship

$$\begin{aligned} \xi(t) &= \Sigma K_1 \cos \Theta_1(t) \\ v(t) &= \Sigma K_2 \sin \Theta_2(t) \\ s(t) = \zeta(\tau) &= \Sigma K_3 \sin \Theta_3(\tau) \end{aligned} \quad (11)$$

where the right-hand sides are the result of computing the series given in Table 8. The third equation for $s(t)$ employs the time-completed $\tau = t + v/n$ to evaluate the series for $\zeta(\tau)$ and thus to obtain $s(t)$.

The adjustable parameters ε and β for ephemerides E5 in the B1950 frame are given in Table 6. The derived values of the angular variables for E5 are given in Table 7.

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Table 8. continued

Table with columns: Index, E5, Argument, Ratio n/n_sat. Contains data for E5 and LAT-3 series coefficients for z3/a3 (sine).

Table with columns: Index, E5, Argument, Ratio n/n_sat. Contains data for V-4 series coefficients for v4 - l4 (sine).

Table with columns: Index, E5, Argument, Ratio n/n_sat. Contains data for XI-4 series coefficients for xi4 = (rho4 - a4)/a4 (cosine).

Table with columns: Index, E5, Argument, Ratio n/n_sat. Contains data for LAT-4 series coefficients for lambda4 = z4/a4 (sine).